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(54) Abstract Title

Electrically controlling multiple downhole devices

(57) A production well control system 10 for electrically controlling multiple downhole devices (41, figure 2) individually or as a group comprises a surface control unit 12, a downhole control module 30 and multiple interface units 40, 50 etc. The operator inputs a command or request to the surface control unit which is passed to a power and communication system 14. The power and communication system generates a command signal of sufficiently high voltage to be sent downhole to the control module 30 which interprets and reformats the signal. The control module is connected to the multiple interface units, each of which is associated with a valve 41. Each interface unit is programmed to respond to a certain signal, energising its particular valve and transmitting data back to the control module 30. Alternatively, the valves are automatically actuated by the sensing of a downhole parameter such as temperature or pressure.

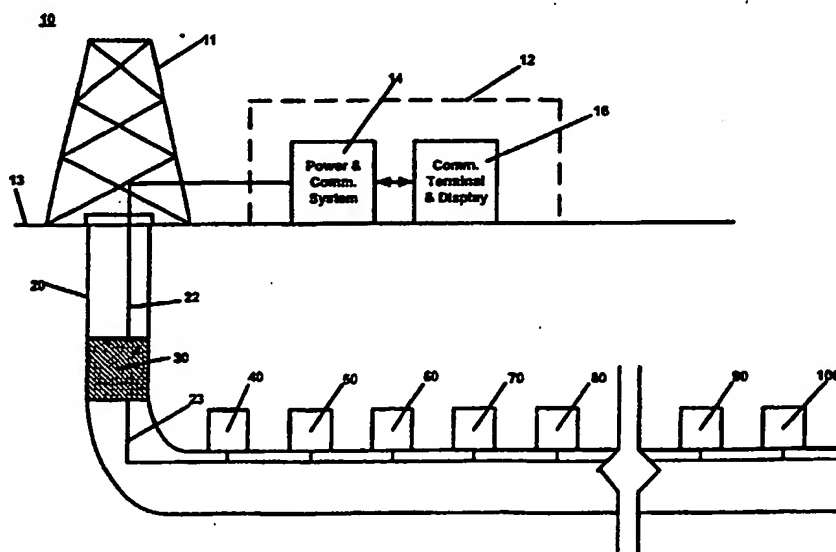


Figure 1

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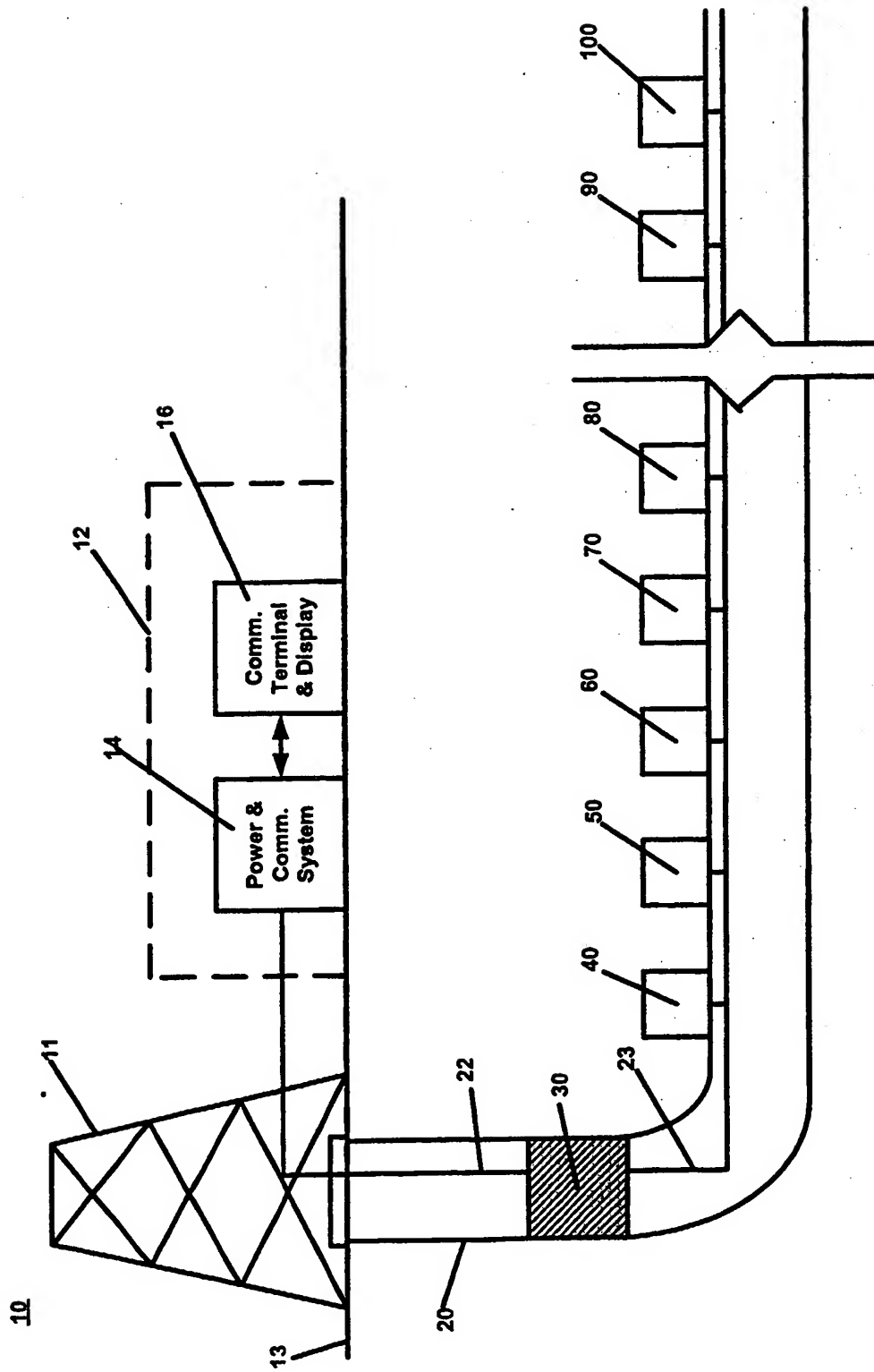


Figure 1

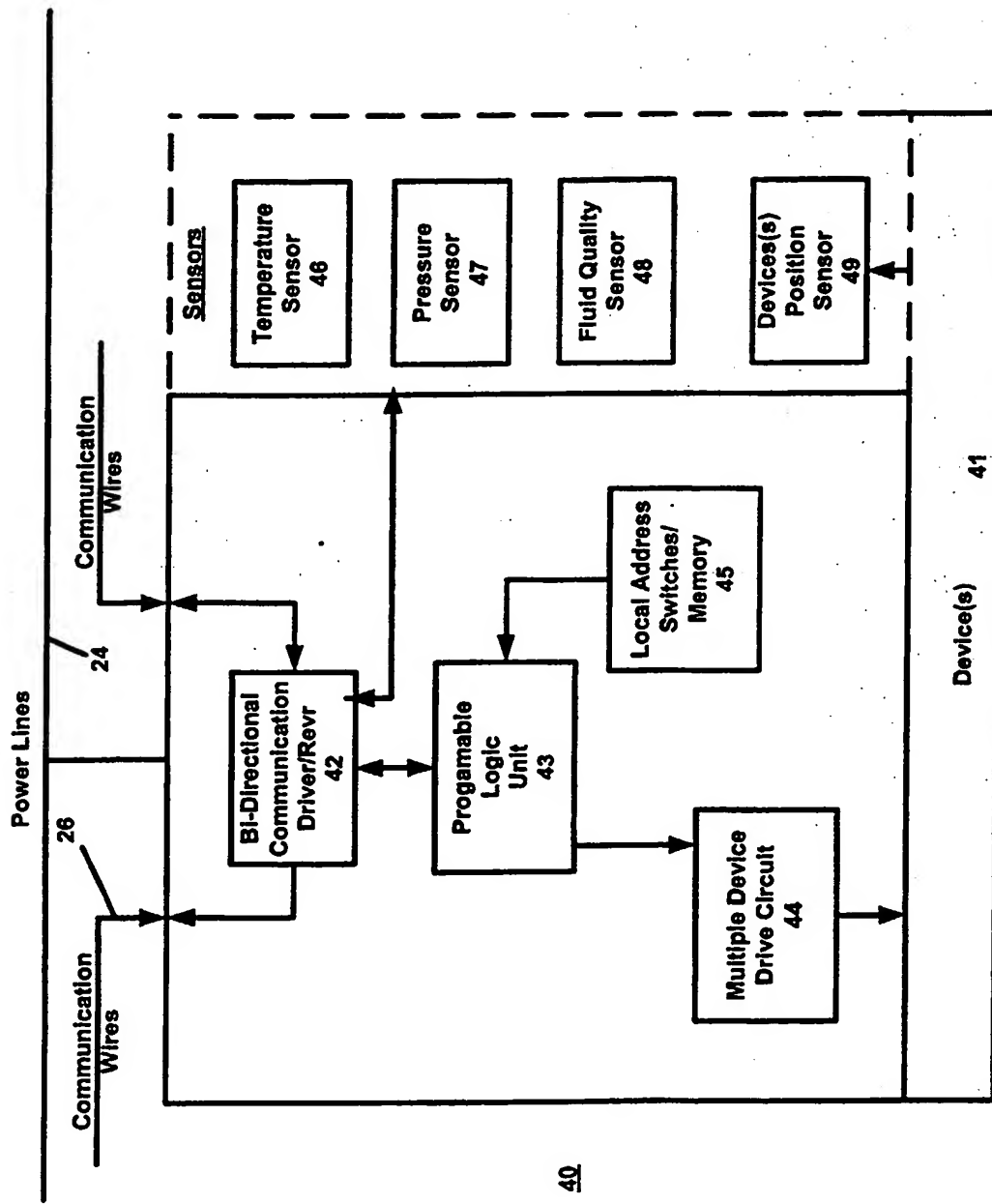


Figure 2

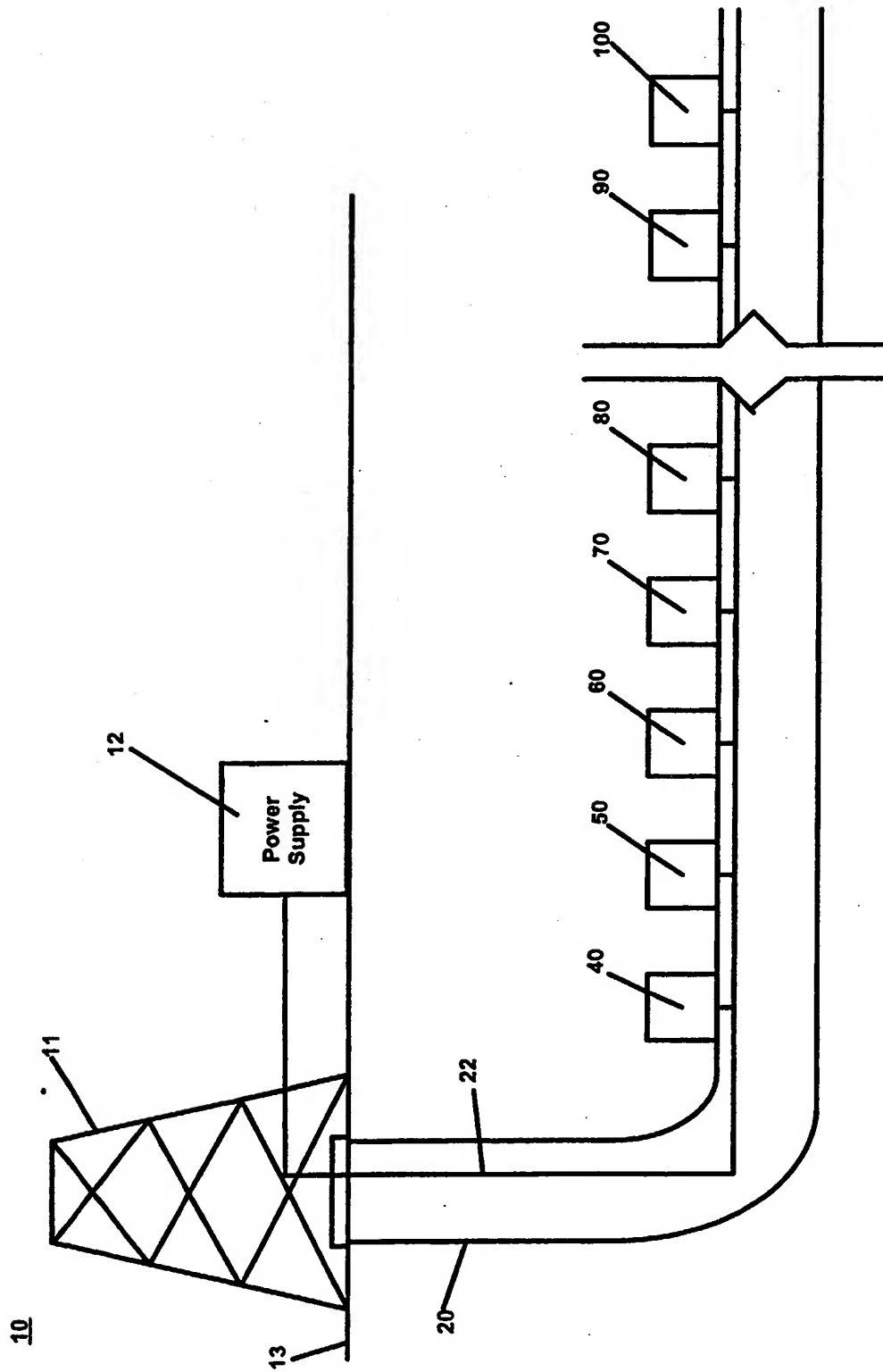
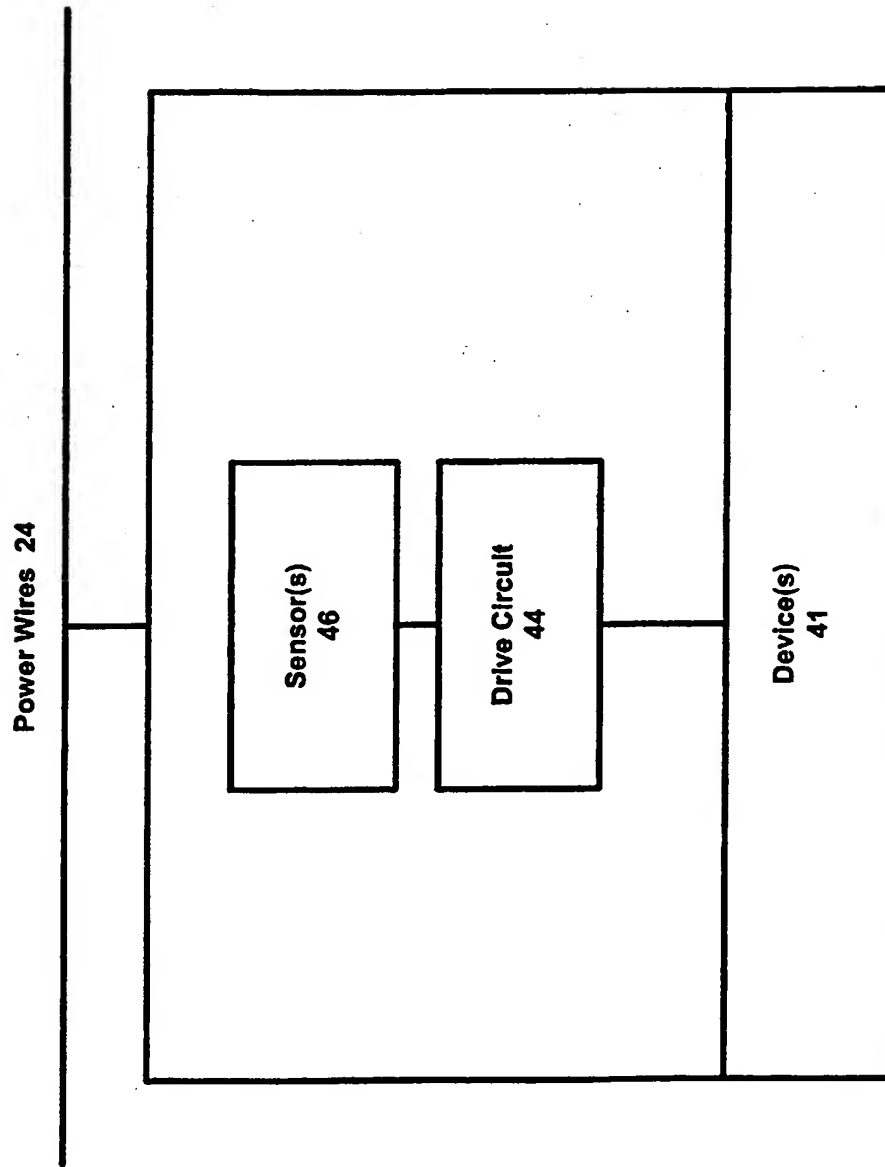


Figure 3



40

Figure 4

1 APPARATUS AND METHOD FOR ELECTRICALLY CONTROLLING
2 MULTIPLE DOWNHOLE DEVICES

3
4 BACKGROUND OF THE INVENTION

5
6 Field of the Invention

7 This invention relates generally to oilfield well
8 operations and more particularly to an apparatus and
9 method for electrically controlling multiple
10 downhole devices.

11
12 Description of the Related Art

13 The control of oil and gas production wells
14 constitutes an on-going concern of the petroleum
15 industry due, in part, to the enormous monetary
16 expense involved as well as the risks associated
17 with environmental and safety issues.

18
19 It will be appreciated that relatively simple, timed
20 intermittent operation of valves and the like are
21 often not adequate to control either outflow from
22 the well or injection to the well so as to optimize
23 well production. As a consequence, sophisticated
24 computerized controllers have been positioned at the
25 surface of production wells for control of downhole
26 devices such as motor valves.

27
28 Surface controllers are often hardwired to downhole
29 sensors which transmit information to the surface
30 such as pressure, temperature and flow. This data
31 is then processed at the surface by the computerized
32 control system.

1
2 While it is well recognized that petroleum
3 production wells will have increased production
4 efficiencies and lower operating costs if surface
5 computer based controllers and downhole
6 microprocessor controllers (actuated by external or
7 surface signals) are utilized, current control
8 systems nevertheless suffer from drawbacks and
9 disadvantages. For example, reliability of surface
10 to downhole signal integrity in a surface control
11 system wherein a downhole microprocessor is actuated
12 by a surface signal is a major concern. It will be
13 appreciated that should the surface signal be in any
14 way compromised on its way downhole, then important
15 operations will not take place as needed.
16
17 Prior art surface control systems generally require
18 a surface platform at each well for supporting the
19 control electronics and associated equipment.
20 However, in many instances, the well operator would
21 rather forego building and maintaining a costly
22 platform. Thus, a problem is encountered in that
23 use of present surface controllers require the
24 presence of a location for the control system,
25 namely the platform.
26
27 Disadvantages of present production well control
28 systems involves the extremely high cost associated
29 with implementing changes in well control and
30 related workover operations. Presently, if a
31 problem is detected at the well, the customer is
32 required to send a rig to the wellsite at an

1 extremely high cost (e.g., 5 million dollars for 30
2 days offshore work). The well must then be shut in
3 during the workover causing a large loss in revenues
4 (e.g., 1.5 million dollars for a 30 day period).
5 Associated with these high costs are the relatively
6 high risks of adverse environmental impact due to
7 spills and other accidents as well as potential
8 liability of personnel at the rig site. Of course,
9 these risks can lead to even further costs. Because
10 of the high costs and risks involved, in general, a
11 customer may delay important and necessary workover
12 of a single well until other wells in that area
13 encounter problems. This delay may cause the
14 production of the well to decrease or be shut in
15 until the rig is brought in.

16

17 SUMMARY OF THE INVENTION

18 The present invention provides a production well
19 control system for controlling multiple downhole
20 devices, preferably, but not limited to, valves,
21 separated by thousands of meters. This system
22 allows for economic, reliable and reversible means
23 of controlling a plurality of downhole devices.

24

25 In accordance with a first embodiment of the present
26 invention, a surface control unit, downhole control
27 module and interface unit are provided for
28 selectively controlling downhole devices. An
29 important feature of this invention is the ability
30 to access individually, or as a group, multiple
31 devices (e.g., valves) arranged in a distributed
32 scheme. The number of downhole devices that can be

1 controlled by this apparatus is only limited by the
2 data address sizes, the power delivered and the
3 power consumed. Additionally, the apparatus is
4 inherently more reliable with each downhole device
5 electrically coupled to an interface unit having a
6 unique, stored address which must correspond to a
7 surface transmitted address before actuation of the
8 downhole device.

9
10 In accordance with a second embodiment of the
11 present invention, comprising downhole sensors,
12 downhole devices and a downhole control module
13 whereby the control module automatically controls
14 the downhole devices based upon a sensed downhole
15 parameter or event. Therefore, using downhole
16 sensors, the downhole control module will monitor
17 actual downhole parameters (e.g., pressure,
18 temperature, flow) and automatically execute control
19 instructions to activate the downhole devices when
20 parameters reach a preset limit or are outside of an
21 optimum operating range.

22
23 In contrast to the first embodiment, well control
24 systems which consist of a control module located
25 wholly at the surface and a downhole computer system
26 which requires an external initiation signal (as
27 well as a surface control system), the downhole well
28 production control system in the second embodiment
29 automatically operates based on downhole conditions
30 sensed in real time without the need for a surface
31 or external signal. This important feature
32 constitutes a significant advance in the field of

1 production well control. Additional advantages of
2 this system include elimination of the need for a
3 surface platform and an even more reliable
4 communication system since no surface to downhole
5 actuation signal is required and the associated risk
6 that such an actuation signal will be compromised is
7 therefore rendered moot.

8
9 A power source provides energy to the downhole
10 control unit in both embodiments described below.
11 Power for the power source can be generated,
12 preferably, at the surface or in the wellbore (e.g.,
13 by a turbine generator) or supplied by energy
14 storage devices such as batteries (or a combination
15 of one or more power sources). The power source
16 provides electrical voltage and current to the
17 downhole electronics, electromechanical devices and
18 sensors in the wellbore.

19
20 Examples of the more important features of the
21 invention thus have been summarized rather broadly
22 in order that the detailed description thereof that
23 follows may be better understood, and in order that
24 the contributions to the art may be appreciated.
25 There are, of course, additional features of the
26 invention that will be described hereinafter and
27 which will form the subject of the claims appended
28 hereto.

29

30 BRIEF DESCRIPTION OF THE DRAWINGS

31 For detailed understanding of the present invention,
32 references should be made to the following detailed

1 description of the preferred embodiment, taken in
2 conjunction with the accompanying drawings, in which
3 like elements have been given like numerals and
4 wherein:

5

6 **FIGURE 1** is a schematic diagram of a production
7 system that employs the apparatus of the present
8 invention;

9

10 **FIGURE 2** is a block diagram showing an interface
11 unit in accordance with the present invention;

12

13 **FIGURE 3** is a schematic diagram of the production
14 system that employs an alternative embodiment of the
15 present invention; and

16

17 **FIGURE 4** is a block diagram showing a control unit
18 of the alternative embodiment.

19

20 **DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENT**

21 **Figure 1** is a schematic diagram of a production
22 system 10, including a conventional derrick 11. A
23 surface control unit 12 at the surface allows an
24 operator to generate a command/request to be
25 executed downhole. The operator may request
26 downhole data or actuate one or more downhole
27 devices by inputting a command into a communication
28 terminal and display 16. The command is
29 communicated by wire or wireless to a power and
30 communication system 14.

31

1 The power and communication system 14 generates a
2 command sequence and sufficient voltage to drive the
3 selected downhole device. Specifically, the power
4 and communication system 14 encodes the operator's
5 command as a command signal using a synchronized
6 communication technique, preferably Manchester data
7 encoding. The power and communication system 14
8 also generates a sufficiently high voltage to ensure
9 that the command signal and activation voltage
10 arrive at a downhole control module 30. The command
11 signal and activation voltage are transmitted from
12 the power and communication system 14 to the
13 downhole control module 30 via twisted pair wiring
14 housed in armored and shielded lines 22 extending
15 downward from the surface 13 into the wellbore 20.

16
17 Upon receipt of the command signal and activation
18 voltage, the downhole control module 30 interprets
19 and reformats the command signal before transmitting
20 a command serial data package and the activation
21 voltage via armored and shielded lines 23,
22 comprising a bi-directional four wire communication
23 path comprising two wires for communicating power,
24 one wire for communicating a clock pulse and one
25 wire for communicating data. Power lines 24 and
26 communication lines (e.g., clock pulse wire and data
27 wire) 26, shown in Figure 2, are connected to an
28 interface unit 40 which is electrically coupled to
29 at least one downhole device 41, preferably, but not
30 limited to, a valve. Returning to Figure 1, the
31 downhole control module 30 may transmit the command
32 signal and activation voltage to multiple interface

1 units 40, 50, 60, 70, 80, 90 and 100 in a
2 distributed control scheme.

3
4 As shown in Figure 2, the interface unit 40,
5 comprises a bi-directional communication transmitter
6 and receiver or transceiver 42 which receives and
7 transmits the data and clock pulse from
8 communication line 26. The receiver/transmitter or
9 transceiver 42 allows data to travel bi-
10 directionally through the armored and shielded wire
11 23 in a half duplex manner. A programmable logic unit
12 43, within the interface unit 40, decodes the
13 address and clock and compares the transmitted
14 address in the command serial stream to the local
15 address stored in memory 45. The local address is
16 either electrically programmed before or after the
17 interface unit 40 is placed downhole or hardwired
18 into the interface unit 40 prior to placement
19 downhole.

20
21 If the transmitted address in the command serial
22 stream and the stored address in the interface unit
23 40 are equivalent, and depending upon the operator's
24 command/request, the downhole device drive circuit
25 44 will be energized and the downhole device 41
26 actuated (i.e., opens, closes, partially opens or
27 closes) or data may be obtained from various
28 downhole sensors including, but not limited to, a
29 temperature sensor 46, pressure sensor 47, fluid
30 sensor 48 and/or downhole device position sensor 49.
31 This data is then transmitted to the downhole
32 control module 30 and the surface control unit 12.

1
2 If the transmitted address in the command serial
3 stream does not correspond to the stored address in
4 the interface unit 40, the bi-directional
5 transceiver 42 transmits the command serial stream
6 to the next interface unit 50 downstream. Following
7 this transmission, the transmitter portion of the
8 transceiver 42 is de-energized and the receiver
9 portion is energized. This process continues until
10 the command serial stream reaches the appropriate
11 interface unit containing the identical address as
12 the transmitted address in the command serial
13 stream.

14
15 Figure 3 illustrates an alternative embodiment of
16 the present invention. As in the first embodiment,
17 the alternative embodiment includes a production
18 system 10 comprising, in part, a conventional
19 derrick 11. However, unlike the first embodiment,
20 the alternative embodiment does not require
21 transmission of surface commands since actuation of
22 the downhole device or group of downhole devices is
23 initiated upon the sensing of a preset downhole
24 parameter (e.g., temperature, pressure, flow or
25 change in position of the downhole device) or event.

26
27 Preferably, a power supply 12 is located at the
28 surface to generate sufficient power to drive a
29 downhole control unit 40 and at least one downhole
30 device 41. The power from the supply 12 is
31 transmitted via armored and shielded lines 22
32 extending downward from the surface 13 into the

1 wellbore 20 to the downhole control unit 40 and at
2 least one downhole device 41. However, it is
3 contemplated that power for the power supply can be
4 generated in the wellbore (e.g., by a turbine
5 generator) or supplied by energy storage devices
6 such as batteries (or a combination of one or more
7 power sources).

8
9 **Figure 4** illustrates a block diagram of the downhole
10 control unit 40, comprising a sensor device 46 and a
11 drive circuit 44. As mentioned above, the downhole
12 control unit 40 operates autonomously by sensing a
13 preset downhole parameter, (i.e., temperature,
14 pressure, flow, position or other area of interest)
15 and actuating the downhole device 41. For example,
16 in controlling flow through a valve which is prone
17 to heat up or cool down due to pressure differences
18 on either side of the valve, a silicone diode
19 temperature switch or a bi-metal thermostat may be
20 used as the sensing device 46. Upon sensing a
21 preset temperature, the sensor device 46 switches
22 from an open state to a closed state permitting
23 power from lines 24 to reach the drive circuit 44
24 and activation (e.g., opening, closing, partially
25 opening or partially closing) of at least one
26 downhole device 41 (or multiple downhole devices)
27 based upon the downhole parameter or event.

28
29 The foregoing description is directed to particular
30 embodiments of the present invention for the purpose
31 of illustration and explanation. It will be
32 apparent, however, to one skilled in the art that

1 many modifications and changes to the embodiment set
2 forth are possible without departing from the scope
3 and the spirit of the invention. It is intended
4 that the following claims be interpreted to embrace
5 all such modifications and changes.

1 CLAIMS

2
3 1. A system for selective control of at least one
4 downhole device among a plurality of downhole
5 devices, comprising:

6 (a) a surface control unit for transmitting a
7 command signal and an activation voltage
8 to a selected downhole device among a
9 plurality of downhole devices;

10 (b) a downhole control module electrically
11 responsive to said surface control unit
12 for receiving, interpreting and
13 reformatting said command signal from said
14 surface control unit said control module
15 transmitting said reformatted command
16 signal and said activation voltage to at
17 least said selected downhole device; and,

18 (c) an interface unit electrically coupled to
19 the selected downhole device for receiving
20 said reformatted command signal,
21 energizing the selected downhole device
22 and transmitting downhole data to said
23 downhole control module.

24
25 2. A system for selective control of at least one
26 downhole device from among a plurality of
27 downhole devices, said system comprising:

28 (a) a surface power source for generating an
29 activation voltage for the at least one
30 downhole device; and,

31 (b) a control unit for sensing at least one
32 downhole condition parameter; said control

1 unit electrically coupled to the one
2 downhole device for activating the one
3 downhole device responsive to a
4 predetermined value of said downhole
5 condition parameter.
6

- 7 3. A method of controlling at least one downhole
8 device, comprising:
9 (a) transmitting a command signal and
10 activation voltage from a surface control
11 unit;
12 (b) receiving said command signal and said
13 activation voltage by a downhole control
14 module;
15 (c) interpreting said command signal by said
16 downhole control module;
17 (d) reformatting said command signal by said
18 downhole control module;
19 (e) transmitting said reformatted command
20 signal and said activation voltage to at
21 least one predetermined downhole device
22 among a plurality of downhole devices;
23 (f) receiving said reformatted command signal
24 at an interface unit electrically coupled
25 to said predetermined downhole device;
26 (g) actuating the predetermined downhole
27 device in response to said reformatted
28 command; and
29 (h) transmitting downhole data from said
30 interface unit to said downhole control
31 module and to said surface control unit.



INVESTOR IN PEOPLE

Application No: GB 0201644.2
Claims searched: 1 and 3

14

Examiner: Matthew Perkins
Date of search: 27 May 2002

Patents Act 1977 Search Report under Section 17

Databases searched:

UK Patent Office collections, including GB, EP, WO & US patent specifications, in:

UK Cl (Ed.T): E1F FKF, FKG, FLM

Int Cl (Ed.7): E21B

Other: Online: WPI, EPODOC, PAJ

Documents considered to be relevant:

Category	Identity of document and relevant passage	Relevant to claims
X	GB 2207161 A (OTIS) See pages 7 to 9	1 & 3

X Document indicating lack of novelty or inventive step
Y Document indicating lack of inventive step if combined with one or more other documents of same category.
& Member of the same patent family

A Document indicating technological background and/or state of the art.
P Document published on or after the declared priority date but before the filing date of this invention.
E Patent document published on or after, but with priority date earlier than, the filing date of this application.

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